Script generated by TTT

Title: Seidl: Virtual_Machines (26.04.2016)

Date: Tue Apr 26 10:22:20 CEST 2016

Duration: 91:14 min

Pages: 36

Actions when terminating the call:

2. Restoring of the registers FP, EP

3. Jumping back into the code of f, i.e., Restauration of the PC

4. Popping the stack

return

} } slide

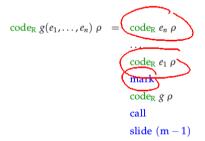
Actions when entering g:

3. Determining the start address of
$$g$$

5. Saving PC and Jump to the beginning of
$$g$$

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Accordingly, we obtain for a call to a function with at least one parameter and one return value:



where m is the size of the actual parameters.

- Similar to declared arrays, function names are interpreted as constant pointes onto function code. Thus, the R-value of this pointer is the start address of the function.
- Caveat! For a variable int (*)() g; the two calls

$$(*g)()$$
 und $g()$

are equivalent! By means of normalization, the dereferencing of function pointers can be considered as redundant.

• During passing of parameters, these are copied.

Consequently,

$$\operatorname{code}_{\mathbb{R}} f \rho = \operatorname{loadc} (\rho f)$$
 f name of a function $\operatorname{code}_{\mathbb{R}} (*e) \rho = \operatorname{code}_{\mathbb{R}} e \rho$ e function pointer $\operatorname{code}_{\mathbb{R}} e \rho = \operatorname{code}_{\mathbb{L}} e \rho$

move k e a structure of size k

where

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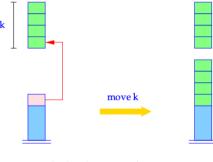
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where

Remark

- Of every expression which is passed as a parameter, we determine the R-value
 call-by-value passing of parameters.
- The function g may as well be denoted by an expression, whose R-value provids the start address of the called function ...

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for (i = k-1; i
$$\geq$$
0; i--)
S[SP+i] = S[S[SP]+i];
SP = SP+k-1;

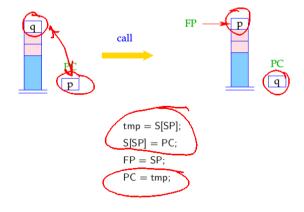
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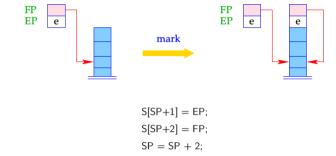


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The instruction $\;\;$ call $\;$ saves the return address and sets FP and PC onto the new values.

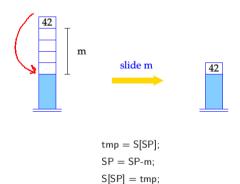


The instruction mark saves the registers FP and EP onto the stack.

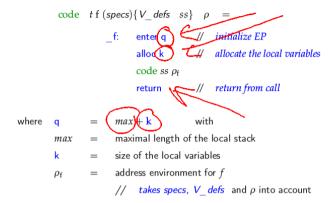


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The instruction slide copies the return values into the correct memory cell:

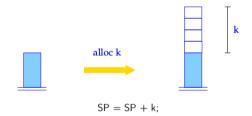


Accordingly, we translate a function definition:

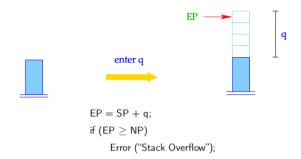


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The instruction alloc k allocates memory for locals on the stack.

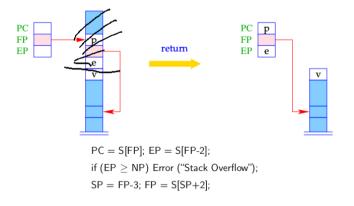


The instruction enter q sets the EP to the new value. If not enough space is available, program execution terminates.



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The instruction return pops the current stack frame. This means it restores the registers PC, EP and FP and returns the return value on top of the stack.



9.4 Access to Variables, Formal Parameters and Returning of Values

Accesses to local variables or formal parameters are relative to the current FP. $Accordingly, \ we \ modify \ code_L \ for \ names \ of \ variables.$

For
$$\rho x = (tag, j)$$
 we define
$$\operatorname{code}_{\mathbb{L}} x \, \rho = \left\{ \begin{array}{ll} \operatorname{loadc} j & tag = G \\ \operatorname{loadr} j & tag = L \end{array} \right.$$

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As an optimization, we introduce analogously to loada j and storea j the new instructions loadr j and storer j :

The instruction loadrc j computes the sum of FP and j.



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The code for e; corresponds to an assignment to a variable with relative address -3.

```
\begin{array}{rcl} \operatorname{code} \, \operatorname{return} e; \; \rho & = & \operatorname{code}_{\mathbb{R}} e \; \rho \\ & \operatorname{storer} \; \text{-3} \\ & \operatorname{return} \end{array}
```

Example For function

```
int fac (int x) { if (x \le 0) return 1; else return x * \mathrm{fac}\ (x-1); }
```

we generate:

where
$$\rho_{\text{fac}}: x \mapsto (L, -3)$$
 and $q = 5$.

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Then we define:

$$\operatorname{code} p \emptyset = \operatorname{enter} (k+4)$$

$$\operatorname{alloc} (k+1)$$

$$\operatorname{mark}$$

$$\operatorname{loadc_main}$$

$$\operatorname{call}$$

$$\operatorname{slide} k$$

$$\operatorname{halt}$$

$$\underline{ f_1:} \operatorname{code} F_- \operatorname{def_1} \rho$$

$$\vdots$$

$$\underline{ f_n:} \operatorname{code} F \operatorname{def_n} \rho$$

 $\begin{array}{cccc} \text{where} & \emptyset & \widehat{=} & \text{empty address environment;} \\ & \rho & \widehat{=} & \text{global address environment;} \\ & k & \widehat{=} & \text{size of the global variables} \end{array}$

10 Translation of Whole Programs

Before program execution, we have:

$$SP = -1$$
 $FP = EP = -1$ $PC = 0$ $NP = MAX$

Let $p \equiv V_defs$ $F_def_1 \dots F_def_n$, denote a program where F_def_i is the definition of a function f_i of which one is called main .

The code for the program p consists of:

- code for the function definitions F def;
- code for the allocation of global variables;
- code for the call of int main();
- the instruction halt which returns control to the operating system together with the value at address 0.

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The Translation of Functional Programming Languages

11 The language PuF

We only regard a mini-language PuF ("Pure Functions").

We do not treat, as yet:

- Side effects:
- Data structures;
- Exceptions.

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Example

The following well-known function computes the factorial of a natural number:



As usual, we only use the minimal amount of parenthese

There are two Semantics:

CBV: Arguments are evaluated before they are passed to the function (as in SML);

CBN: Arguments are passed unevaluated; they are only evaluated when their value is needed (as in Haskell).

let rec for X = if

A program is an expression e of the form:

$$e ::= b \mid x \mid (\Box_1 e) \mid (e_1 \Box_2 e_2)$$

$$\mid (if e_0 \text{ then } e_1 \text{ else } e_2)$$

$$\mid (e' e_0 \dots e_{k-1})$$

$$\mid (fun \ x_0 \dots x_{k-1} \to e)$$

$$\mid (let \ x_1 = e_1 \text{ in } e_0)$$

$$\mid (let \text{ rec } x_1 = e_1 \text{ and } \dots \text{ and } x_n = e_n \text{ in } e_0)$$

An expression is therefore

- a basic value, a variable, the application of an operator, or
- a function-application, a function-abstraction, or
- a let-expression, i.e. an expression with locally defined variables, or
- a let-rec-expression, i.e. an expression with simultaneously defined local variables.

For simplicity, we only allow int as basic type.

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Example

The following well-known function computes the factorial of a natural number:

$$\begin{array}{ll} \mbox{let rec} \mbox{ fac} & = & \mbox{ fun } x \to \mbox{if } x \leq 1 \mbox{ then } 1 \\ \\ & \mbox{ else } x \cdot \mbox{fac } (x-1) \end{array}$$

in fac 7

As usual, we only use the minimal amount of parentheses.

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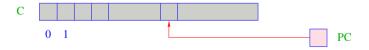




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12 Architecture of the MaMa

We know already the following components:



C = Code-store – contains the MaMa-program; each cell contains one instruction;

PC = Program Counter – points to the instruction to be executed next;

Example

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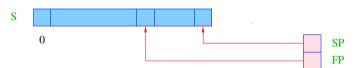
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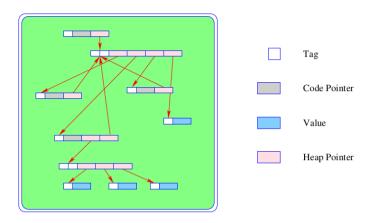


S = Runtime-Stack – each cell can hold a basic value or an address;

SP = Stack-Pointer – points to the topmost occupied cell; as in the CMa implicitely represented;

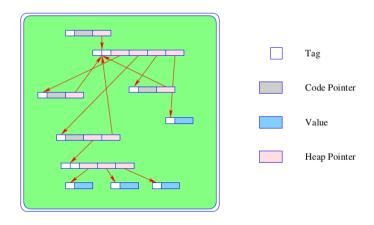
FP = Frame-Pointer – points to the actual stack frame.

We also need a heap H:

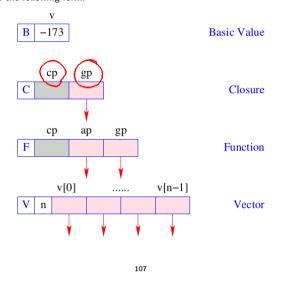


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We also need a heap H:



... it can be thought of as an abstract data type, being capable of holding data objects of the following form:



The instruction new (tag, args) creates a corresponding object (B, C, F, V) in H and returns a reference to it.

We distinguish three different kinds of code for an expression e:

- code_V e (generates code that) computes the Value of e, stores it in the heap and returns a reference to it on top of the stack (the normal case);
- code_B e computes the value of e, and returns it on the top of the stack (only for Basic types);
- code_C e does not evaluate e, but stores a Closure of e in the heap and returns
 a reference to the closure on top of the stack.

We start with the code schemata for the first two kinds:

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