

Title: Seidl: Virtual Machines (16.06.2014)

Date: Mon Jun 16 10:46:44 CEST 2014

Duration: 43:59 min

Pages: 24

41 Calling Member Functions

Static member functions are considered as ordinary functions :-)

For non-static member functions, we distinguish two forms of calls:

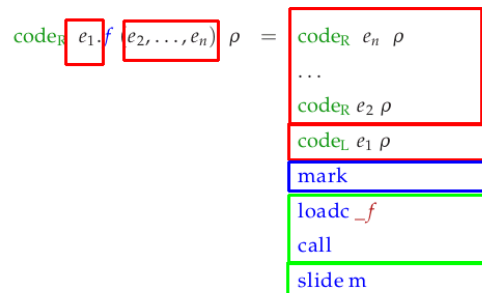
- (1) directly: $f(e_2, \dots, e_n)$
- (2) relative to an object: $e_1.f(e_2, \dots, e_n)$

Idea:

- The case (1) is considered as an abbreviation of $\text{this}.f(e_2, \dots, e_n)$:-)
- The object is passed to f as an implicit first argument :-)
- If f is non-virtual, proceed as with an ordinary call of a function :-)
- If f is virtual, insert an indirect call :-)

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A non-virtual function:



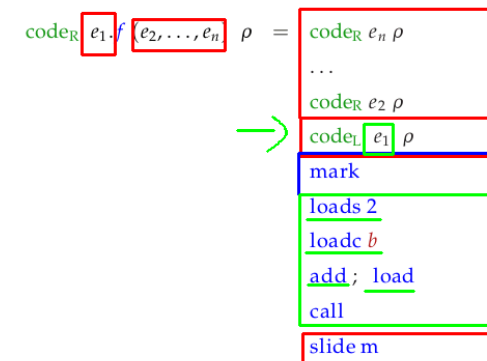
where $(F _f) = \rho_C(f)$
 $C = \text{class of } e_1$
 $m = \text{space for the actual parameters}$

Note:

The pointer to the object is obtained by computing the L-value of e_1 :-)

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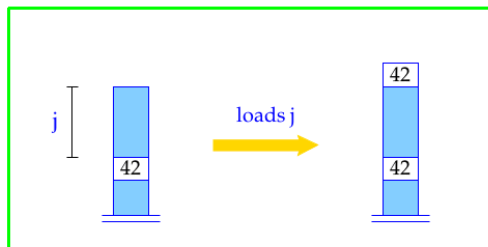
A virtual function:



where $(V, b) = \rho_C(f)$
 $C = \text{class of } e_1$
 $m = \text{space for the actual parameters}$

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The instruction `loads j` loads relative to the stack pointer:



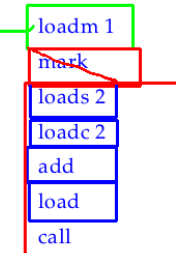
$S[SP+1] = S[SP-j];$
 $SP++;$

... in the Example:

The recursive call

`next` → `last ()`

in the body of the virtual method `last` is translated into:



42 Defining Member Functions

In general, a definition of a member function for class `C` looks as follows:

$d \equiv t f (t_2 x_2, \dots, t_n x_n) \{ ss \}$

Idea:

- `f` is treated like an ordinary function with one extra implicit argument
- Inside `f` a pointer `this` to the current object has relative address -3 :-)
- Object-local data must be addressed relative to `this ...`

```
codeD d ρ = _f : enter q // Setting the EP
                alloc m // Allocating the local variables
                code ss ρ1
                return // Leaving the function
```

where `q` = `maxS + m` where
`maxS` = maximal depth of the local stack
`m` = space for the local variables
`k` = space for the formal parameters (including `this`)
`ρ1` = local address environment

... in the Example:

_last:	enter 6	loadm 0	loads 2
	alloc 0	storer -3	loadc 2
	loadm 1	return	add
	loadc 0		load
	eq	A: loadm 1	call
	jumpz A	mark	storer -3
			return

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A virtual function:

$$\text{code}_R e_1.f(e_2, \dots, e_n) \rho = \text{code}_R e_n \rho$$

$$\dots$$

$$\text{code}_R e_2 \rho$$

$$\text{code}_L e_1 \rho$$

mark
loads 2
loadc b
add; load
call
slide m

where $(V, b) = \rho_C(f)$

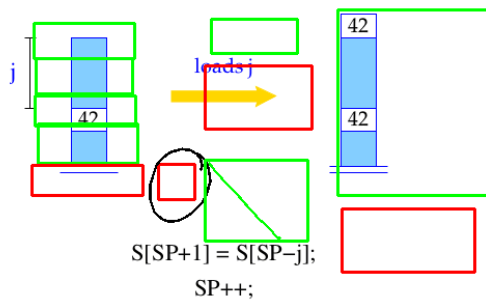
C = class of e_1

m = space for the actual parameters

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The instruction `loads j` loads relative to the stack pointer.

Handwritten: `if (next == 0) return into;`
Handwritten: `else return next -> get();`



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43 Calling Constructors

Every new object should be initialized by (perhaps implicitly) calling a constructor. We distinguish two forms of object creations:

- (1) directly: `x = C(e2, ..., en);`
- (2) indirectly: `new C(e2, ..., en)`

Idea for (2):

- Allocate space for the object and return a pointer to it on the stack;
- Initialize the fields for virtual functions;
- Pass the object pointer as first parameter to a call to the constructor;
- Proceed as with an ordinary call of a (non-virtual) member function :-)
- Unboxed objects are considered later ...

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```

codeR new C (e2, ..., en) ρ = loadc |C|
                               new
                               initVirtual C
                               codeR en ρ
                               ...
                               codeR e2 ρ
                               loads m // loads relative to SP :-)
                               mark
                               loadc _C
                               call
                               pop m + 1

```

where m = space for the actual parameters.

Before calling the constructor, we initialize all fields of virtual functions.

The pointer to the object is copied into the frame by an extra instruction :-)

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Assume that the class C lists the virtual functions f_1, \dots, f_r for C with the offsets and initial addresses: b_i and a_i , respectively:

Then:

```

initVirtual C = dup
                loadc b1; add
                loadc a1; store
                pop
                ...
                dup
                loadc br; add
                loadc ar; store
                pop

```

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```

codeR new C (e2, ..., en) ρ = loadc |C|
                               new
                               initVirtual C
                               codeR en ρ
                               .
                               codeR e2 ρ
                               loads m // loads relative to SP :-)
                               mark
                               loadc _C
                               call
                               pop m + 1

```

(Handwritten red annotations: a box around the 'new' instruction, a box around the 'initVirtual C' instruction, a box around the 'code_R e_n ρ' instruction, a box around the 'code_R e₂ ρ' instruction, a box around the 'loads m' instruction, a box around the 'pop m + 1' instruction, and a red arrow pointing to the 'loads m' instruction.)

where m = space for the actual parameters.

Before calling the constructor, we initialize all fields of virtual functions.

The pointer to the object is copied into the frame by an extra instruction :-)

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Assume that the class C lists the virtual functions f_1, \dots, f_r for C with the offsets and initial addresses: b_i and a_i , respectively:

Then:

```

initVirtual C = dup
                loadc b1; add
                loadc a1; store
                pop
                ...
                dup
                loadc br; add
                loadc ar; store
                pop

```

(Handwritten blue annotations: boxes around the 'dup' instruction, the 'loadc b₁; add' instruction, the 'loadc a₁; store' instruction, the 'dup' instruction, the 'loadc b_r; add' instruction, and the 'loadc a_r; store' instruction. Red circles around 'a₁' and 'a_r' with arrows pointing to the 'store' instructions.)

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44 Defining Constructors

In general, a definition of a constructor for class `C` looks as follows:

$$d \equiv C(t_2\ x_2, \dots, t_n\ x_n)\ \{ss\}$$

Idea:

- Treat the constructor as a definition of an ordinary member function :-)

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... in the Example:

```

_list:  enter 3   loada 1   loadc 0
        alloc 0   loadc 1   storem 1
        loadr -4  add       pop
        storem 0  storea 1  return
        pop      pop
    
```

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44 Defining Constructors

In general, a definition of a constructor for class `C` looks as follows:

$$d \equiv C(t_2\ x_2, \dots, t_n\ x_n)\ \{ss\}$$

Idea:

- Treat the constructor as a definition of an ordinary member function :-)

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40 Object Layout

Idea:

- Only attributes and **virtual** member functions are stored inside the class !!
- The addresses of **non-virtual** or **static** member functions, as well as of constructors can be resolved at compile time
- The fields of a sub-class are **appended** to the corresponding fields of the super-class ...

... in our Example:

info
next
last



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Discussion:

The constructor may issue further constructors for attributes if desired :-)

The constructor may call a constructor of the super class B as first action:

```
code B (e2, ..., en); ρ =
  codeR en ρ
  ...
  codeR e2 ρ
  loadR - 3
  mark
  loadC _B
  call
  pop m + 1
```

where m = space for the actual parameters.

The constructor is applied to the current object of the calling constructor!

45 Initializing Unboxed Objects

Problem:

The same constructor application can be used for initializing several variables:

$$x = x_1 = C(e_2, \dots, e_n)$$

Idea:

- Allocate sufficient space for a **temporary copy** of a new C object.
- Initialize the temporary copy.
- Assign this value to the variables to be initialized :-)

```
codeR C (e2, ..., en) ρ =
  stalloc |C|
  initVirtual C
  codeR en ρ
  ...
  codeR e2 ρ
  loadS m
  mark
  loadC _C
  call
  pop m + 2
```

where m = space for the actual parameters.

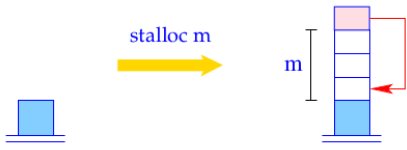
Note:

The instruction `stalloc m` is like `malloc m` but allocates on the stack :-)

We assume that we have assignments between complex types :-)



SP = SP+m+1;
S[SP] = SP-m;



$SP = SP + m + 1;$
 $S[SP] = SP - m;$