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## Chapter 9

# Priority Queues

173

15 Priority Queues

16 Leftist Heap

17 Priority Queue via Braun Tree

18 Binomial Heap

19 Skew Binomial Heap

174

## Priority queue informally

Collection of elements with priorities

176

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Collection of elements with priorities

Operations:

176

## Priority queue informally

Collection of elements with priorities

Operations:

- empty
- emptiness test
- insert
- get element with minimal priority
- delete element with minimal priority

We focus on the priorities:

element = priority

176

## Priority queues are multisets

The same element can be contained **multiple times**  
in a priority queue

177

## Interface of implementation

The type of elements (= priorities)  $'a$  is a linear order

178

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An implementation of a priority queue of elements of type  $'a$  must provide

178

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An implementation of a priority queue of elements of type  $'a$  must provide

- An implementation type  $'q$

178

## More operations

- $merge :: 'q \Rightarrow 'q \Rightarrow 'q$   
Often provided

179

## More operations

- $merge :: 'q \Rightarrow 'q \Rightarrow 'q$   
Often provided
- decrease key/priority  
A bit tricky in functional setting

179

## Correctness of implementation

A priority queue represents a **multiset** of priorities.  
Correctness proof requires:

Abstraction function:  $mset :: 'q \Rightarrow 'a \text{ multiset}$

180

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Abstraction function:  $mset :: 'q \Rightarrow 'a \text{ multiset}$

Invariant:  $invar :: 'q \Rightarrow \text{bool}$

180

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Must prove  $invar\ q \implies$

181

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$mset\ empty = \{\#\}$

181

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$\text{invar empty}$

$\text{invar } (\text{insert } x \ q)$

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181

## Terminology

A binary tree is a *heap* if for every subtree the root is  $\leq$  all elements in that subtree.

182

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182

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The term “heap” is frequently used synonymously with “priority queue”.

182

## Priority queue via heap

- $empty = \langle \rangle$

183

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183

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- $insert\ a\ t = merge\ \langle \langle \rangle, a, \langle \rangle \rangle\ t$

183

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183

## Priority queue via heap

A naive merge:

$merge\ t_1\ t_2 = (\text{case } (t_1, t_2) \text{ of}$   
 $\langle \rangle, - \Rightarrow t_2 \mid$   
 $-, \langle \rangle \Rightarrow t_1 \mid$

184

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  if  $a_1 \leq a_2$  then  $\langle merge\ l_1\ r_1, a_1, t_2 \rangle$   
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184

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**Challenge:** how to maintain some kind of balance

184



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184

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185

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   $(\langle l_1, a_1, r_1 \rangle, \langle l_2, a_2, r_2 \rangle) \Rightarrow$   
    if  $a_1 \leq a_2$  then  $\langle \text{merge } l_1 r_1, a_1, t_2 \rangle$   
    else  $\langle t_1, a_2, \text{merge } l_2 r_2 \rangle$ 
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184

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The *rank* of a tree is the depth of the rightmost leaf.

187

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Merge descends along the right spine.  
Thus rank bounds number of steps.

187

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The *rank* of a tree is the depth of the rightmost leaf.

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Merge descends along the right spine.  
Thus rank bounds number of steps.

If rank of right child gets too large: swap with left child.

187

## Implementation type

**datatype**

$'a \text{ heap} = \text{Leaf} \mid \text{Node } ('a \text{ tree}) 'a \text{ nat } ('a \text{ tree})$

188

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Abbreviations  $\langle \rangle$  and  $\langle l, a, n, r \rangle$  as usual

Abstraction function:

$mset\_tree :: 'a \text{ heap} \Rightarrow 'a \text{ multiset}$

$mset\_tree \langle \rangle = \{\#\}$

$mset\_tree \langle l, a, -, r \rangle =$

$\{\#a\#\} + mset\_tree \ l + mset\_tree \ r$

188

## Leftist tree

$rank :: 'a \text{ heap} \Rightarrow \text{nat}$

189

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$rank :: 'a\ heap \Rightarrow nat$   
 $rank \langle \rangle = 0$   
 $rank \langle -, -, -, r \rangle = rank\ r + 1$

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Node  $\langle l, a, n, r \rangle$ :  $n = \text{rank of node}$

189

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 $rank \langle \rangle = 0$   
 $rank \langle -, -, -, r \rangle = rank\ r + 1$

Node  $\langle l, a, n, r \rangle$ :  $n = \text{rank of node}$

$ltree :: 'a\ heap \Rightarrow bool$   
 $ltree \langle \rangle = True$   
 $ltree \langle l, -, n, r \rangle =$   
 $(n = rank\ r + 1 \wedge rank\ r \leq rank\ l \wedge ltree\ l \wedge ltree\ r)$

189

## Leftist heap invariant

$invar\ h = (heap\ h \wedge ltree\ h)$

190

## merge

Principle: descend on the right

191

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$merge \langle \rangle t_2 = t_2$

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191

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$merge (\langle l_1, a_1, n_1, r_1 \rangle =: t_1) (\langle l_2, a_2, n_2, r_2 \rangle =: t_2) =$

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191

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191

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185

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else *node*  $l_2 a_2$  (*merge*  $t_1 r_2$ ))

*node*  $:: 'a \text{ lheap} \Rightarrow 'a \Rightarrow 'a \text{ lheap} \Rightarrow 'a \text{ lheap}$

*node*  $l a r =$

(let  $rl = rk l; rr = rk r$

in if  $rr \leq rl$  then  $\langle l, a, rr + 1, r \rangle$  else  $\langle r, a, rl + 1, l \rangle$ )

where  $rk \langle -, -, n, - \rangle = n$

191

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192

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Function *merge* terminates because ?  
decreases with every recursive call.

192

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Function *merge* terminates because  $size\ t_1 + size\ t_2$   
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192

## Logarithmic complexity

Correlation of rank and size:

**Lemma**  $ltree\ t \implies 2^{rank\ t} \leq |t|_1$

194

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188

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Correlation of rank and size:

**Lemma**  $l_{tree} t \implies 2^{\text{rank } t} \leq |t|_1$

Complexity measures  $t\_merge$ ,  $t\_insert$   $t\_del\_min$ :  
count calls of  $merge$ .

194

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**Lemma**  $t\_merge l r \leq \text{rank } l + \text{rank } r + 1$

194

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Function  $merge$  terminates because  $size\ t_1 + size\ t_2$   
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192

## Functional correctness proofs

including preservation of *invar*

Straightforward

193



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**Corollary**  $[[ltree\ l; ltree\ r]]$

$\implies t\_merge\ l\ r \leq \log_2 |l|_1 + \log_2 |r|_1 + 1$

**Corollary**

$ltree\ t \implies t\_insert\ x\ t \leq \log_2 |t|_1 + 2$

194

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**Corollary**

$ltree\ t \implies t\_del\_min\ t \leq 2 * \log_2 |t|_1 + 1$

194

## What is a Braun tree?

$braun :: 'a\ tree \implies bool$

198

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$braun\ \langle \rangle = True$

$braun\ \langle l, x, r \rangle =$

$(|r| \leq |l| \wedge |l| \leq |r| + 1 \wedge braun\ l \wedge braun\ r)$

198

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198

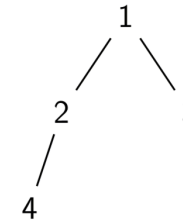
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198

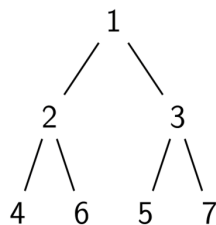
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198

## Idea of invariant maintenance

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199

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Add element:

199

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Add element: to right subtree, then swap subtrees

199

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**Goal:**  $|l| \leq |r| + 1 \wedge |r| + 1 \leq |l| + 1$

199

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**Goal:**  $|l| \leq |r| + 1 \wedge |r| + 1 \leq |l| + 1$

□

199

## Priority queue implementation

Implementation type: *'a tree*

Invariants: *heap* and *braun*

200

## Priority queue implementation

Implementation type: *'a tree*

Invariants: *heap* and *braun*

*No merge*

200

### *insert*

*insert* :: *'a* ⇒ *'a tree* ⇒ *'a tree*

201

### *insert*

*insert* :: *'a* ⇒ *'a tree* ⇒ *'a tree*

*insert* *a* ⟨⟩ = ⟨⟨⟩, *a*, ⟨⟩⟩

*insert* *a* ⟨*l*, *x*, *r*⟩ =

(if *a* < *x* then ⟨*insert* *x* *r*, *a*, *l*⟩ else ⟨*insert* *a* *r*, *x*, *l*⟩)

201

## *del\_min*

*del\_min* :: 'a tree ⇒ 'a tree

202

## *del\_min*

*del\_min* :: 'a tree ⇒ 'a tree

*del\_min* ⟨⟩ = ⟨⟩

*del\_min* ⟨⟨, x, r⟩ = ⟨⟩

*del\_min* ⟨l, x, r⟩ =

(let (y, l') = *del\_left* l in *sift\_down* r y l')

202

## *del\_min*

*del\_min* :: 'a tree ⇒ 'a tree

*del\_min* ⟨⟩ = ⟨⟩

*del\_min* ⟨⟨, x, r⟩ = ⟨⟩

*del\_min* ⟨l, x, r⟩ =

(let (y, l') = *del\_left* l in *sift\_down* r y l')

- 1 Delete leftmost element *y*
- 2 Sift *y* from the root down

Reminiscent of heapsort, but not quite ...

202

## *del\_left*

*del\_left* :: 'a tree ⇒ 'a × 'a tree

203

## *sift\_down*

*sift\_down* :: 'a tree ⇒ 'a ⇒ 'a tree ⇒ 'a tree

204

## *del\_left*

*del\_left* :: 'a tree ⇒ 'a × 'a tree

203

## *sift\_down*

*sift\_down* :: 'a tree ⇒ 'a ⇒ 'a tree ⇒ 'a tree

*sift\_down* ⟨⟩ a ⟨⟩ = ⟨⟨⟩, a, ⟨⟩⟩

*sift\_down* ⟨⟨⟩, x, ⟨⟩⟩ a ⟨⟩ =

(if  $a \leq x$  then ⟨⟨⟨⟩, x, ⟨⟩⟩, a, ⟨⟩⟩

else ⟨⟨⟨⟩, a, ⟨⟩⟩, x, ⟨⟩⟩)

*sift\_down* ⟨⟨ $l_1$ ,  $x_1$ ,  $r_1$ ⟩ =:  $t_1$ ⟩ a ⟨⟨ $l_2$ ,  $x_2$ ,  $r_2$ ⟩ =:  $t_2$ ⟩ =

if  $a \leq x_1 \wedge a \leq x_2$  then ⟨ $t_1$ , a,  $t_2$ ⟩

else if  $x_1 \leq x_2$  then ⟨*sift\_down*  $l_1$  a  $r_1$ ,  $x_1$ ,  $t_2$ ⟩

else ⟨ $t_1$ ,  $x_2$ , *sift\_down*  $l_2$  a  $r_2$ ⟩

204

## *sift\_down*

*sift\_down* :: 'a tree ⇒ 'a ⇒ 'a tree ⇒ 'a tree

*sift\_down* ⟨⟩ a ⟨⟩ = ⟨⟨⟩, a, ⟨⟩⟩

*sift\_down* ⟨⟨⟩, x, ⟨⟩⟩ a ⟨⟩ =

(if  $a \leq x$  then ⟨⟨⟨⟩, x, ⟨⟩⟩, a, ⟨⟩⟩

else ⟨⟨⟨⟩, a, ⟨⟩⟩, x, ⟨⟩⟩)

204

*del\_left*

$del\_left :: 'a\ tree \Rightarrow 'a \times 'a\ tree$

203

Functional correctness proofs  
for *del\_min*

Many lemmas, mostly straightforward

205

Logarithmic complexity

Running time of *insert*, *del\_left* and *sift\_down* (and therefore *del\_min*) bounded by height

206

Logarithmic complexity

Running time of *insert*, *del\_left* and *sift\_down* (and therefore *del\_min*) bounded by height

Remember:  $braun\ t \implies 2^{h(t)} \leq 2 * |t| + 1$

206

## Source of code

Based on code from  
L.C. Paulson. *ML for the Working Programmer*. 1996  
based on code from Chris Okasaki.

207

## Sorting with priority queue

208

## Sorting with priority queue

```
pq [] = empty  
pq (x#xs) = insert x (pq xs)
```

208

## Sorting with priority queue

```
pq [] = empty  
pq (x#xs) = insert x (pq xs)  
  
mins q =  
(if is_empty q then []  
 else get_min h # mins (del_min h))
```

208



## Sorting with priority queue

$pq [] = \text{empty}$   
 $pq (x\#xs) = \text{insert } x (pq \ xs)$

$\text{mins } q =$   
(if  $\text{is\_empty } q$  then []  
else  $\text{get\_min } h \ \# \ \text{mins } (\text{del\_min } h)$ )

$\text{sort\_pq} = \text{mins} \circ \text{pq}$

208

## Sorting with priority queue

$pq [] = \text{empty}$   
 $pq (x\#xs) = \text{insert } x (pq \ xs)$

$\text{mins } q =$   
(if  $\text{is\_empty } q$  then []  
else  $\text{get\_min } h \ \# \ \text{mins } (\text{del\_min } h)$ )

$\text{sort\_pq} = \text{mins} \circ \text{pq}$

Complexity of  $\text{sort}$ :  $O(n \log n)$   
if all priority queue functions have complexity  $O(\log n)$

208

15 Priority Queues

16 Leftist Heap

17 Priority Queue via Braun Tree

18 Binomial Heap

19 Skew Binomial Heap

209

The image shows a presentation slide titled "Priority Queues" with a table of contents on the left and a desktop background on the right. The table of contents includes:

- 15 Priority Queues
- 16 Leftist Heap
- 17 Priority Queue via Braun Tree
- 18 Binomial Heap
- 19 Skew Binomial Heap

The desktop background shows a file explorer window with a list of files and folders, including "Mac OS X", "Documents", "Downloads", "Library", "Music", "Pictures", "Public", "Videos", and "Applications". The slide number "209" is visible in the bottom right corner.